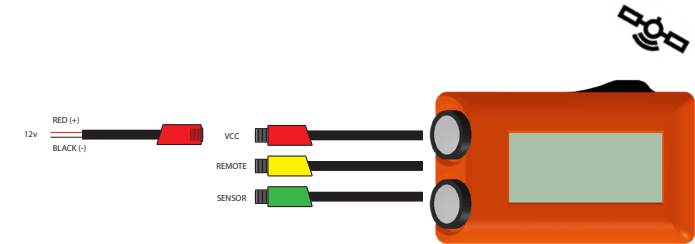




Install

For a correct operation of the equipment it is necessary consider this:

- The top always has to keep the view to the sky, never cover the integrated antenna.
- Use supplied or similar silentblocks.
- The cables should never be forced.
- It is advisable to use fixed power to 12v DC



Start-Up

Once we have connected the equipment will remain on whenever it has activity.

The display will flash until you acquire a GPS signal, during this process will indicate the number of visible satellites, so we can also check the correct operation. The first time it starts, it is normal to delay the acquisition of satellites, please be patient.

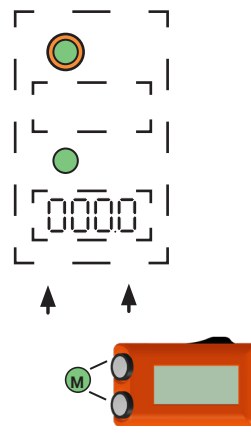
After a period of 20 minutes without activity, it will go to Standby mode, thus saving the data (kmS, Smax ...)

Standby does not show any consumption.

It will start again when it detects movement on the motorcycle or a pulse (+) or (Menu).

To put the equipment in Standby manually we will keep (Menu) +10".

The computer will keep the memory as long as it maintains power, if the 12v are disconnected the records of (kmS, Smax ...) dont be saved.



Working

Odometer: Odocap has the option to operate via GPS or via Sensor. Whenever the GPS signal is available it will prevail over the sensor. In this way if we have the sensor connected and it fails GPS, we will automatically switch to sensor, thus guaranteeing the operation.

Speed: The speed is acquired in the same way as in the Odometer. By giving a long pulse on (+) we will see in the screen the maximum speed (Smax) reached in the last route.

Cap: The grades of compass are shown by GPS, this data will be real whenever we are moving.



MultiView

This function allows us to have several visualizations with fast access for 3" in display.

- **Speed:** Pressing a (+) will show the Cap on screen, while pressing (-) will show the Odometer.
- **Cap:** Pressing a (+) will show the Velocity on screen, while if we press (-) it will show the Odometer.

GZ PARTS OdoCap

FAST USER MANUAL

